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J. Phys. A: Math. Theor. 41 (2008) 035502 (14pp)

doi:10.1088/1751-8113/41/3/035502

# The Hamiltonian formalism and a new type of modulation instability

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Received 16 August 2007, in final form 19 November 2007 Published 4 January 2008 Online at stacks.iop.org/JPhysA/41/035502

#### Abstract

We recently reported the existence of a new type of modulation instability of the waves on the surface of ideal fluid (2006 *J. Phys. A: Math. Gen.* **39** L529). To this end, we considered the system of two equations of motion for the amplitude of the envelope of the first harmonic and for the nonoscillating wave component (zero harmonic) in the framework of the method of multiple scales and the Euler equations of motion. Here, this new type of modulation instability is reproduced with the use of the Zakharov equations for the Fourier amplitudes of the first and zero harmonics on the basis of the Hamiltonian formalism.

PACS numbers: 05.45.-a, 05.45.Yv, 47.35.+i

## 1. Introduction

Stokes' [1] weakly nonlinear periodic solutions to the nonlinear equations describing the wave motion in conservative media are unstable to small harmonic long-wavelength perturbations. This instability was originally discovered for the waves on the surface of an ideal fluid by Lighthill [2], Zakharov [3, 4], Benjamin and Feir [5], Whitham [6], Hasimoto and Ono [7]. Now it is known as the Benjamin–Feir modulation instability (BF MI). It was also found in many other nonlinear media and is a general physical phenomenon. As a result of works [3, 4], it became clear that the analogy between the behaviour of waves of small amplitudes in various media can be explained by a likeness of expansions of the Hamiltonian for waves of the different nature in a power series in a small nonlinearity and the further reformulation of the Euler equations of motion for various waves in the formally identical Hamilton equations. The Hamiltonian theory of waves on the surface of a fluid and in plasma became only the first examples of the general program [3, 4] on the expansion of a Hamiltonian formalism of the nonlinear mechanics of particles onto the wave motion in a continuous medium: the searching for the pairs of canonical variables, the construction of a Hamiltonian of waves in the physical

1751-8113/08/035502+14\$30.00 © 2008 IOP Publishing Ltd Printed in the UK

and Fourier spaces, the determination of the first nonlinear terms of its expansion in a series, and the following derivation of the simplified equations of motion for amplitudes of the lowest harmonics as the Hamilton equations obtained from the Hamiltonian expanded in a series with the truncated upper harmonics (Zakharov equations). In particular, the MI can be investigated from the equations and the coefficients obtained in [3, 4] in the case of a fluid infinite depth. Moreover, a more general type of MI was found in [3, 4] on the basis of interaction of N waves [8], e.g., type II MI [9] with five interacting waves.

The theory [3, 4] was also applied to the case of a fluid of finite depth [10]. Here, except for the strong complication of calculations due to the dependence of coefficients of the Hamiltonian on depth h, there is also the basic difference consisting of the appearance of a non-oscillating component (the zero harmonic which varies, by the terminology of the method of multiple scales, in slower time) among Fourier harmonics. Such component is equal to zero in the case of infinite depth in the considered order of precision. Upper harmonics are removed from the Hamiltonian and equations of motion by means of the reduction of the Hamiltonian. But to make the same with the zero harmonics is possible only at additional assumptions about the character of its time dependence. The elimination of the equation for the zero harmonic can lead to a decrease of the order of the dispersion equation and, thus, to losses of a part of its solutions. The necessity of an accurate treatment of the equation for the zero harmonic was also discussed outside of the Hamiltonian approach [11–14]. In [10], the reduction of a Hamiltonian was not executed and the equation for a zero harmonic was maintained, which would allow one to consider a wide spectrum of problems. However, the analytic evaluations involved only the zone of wave vectors of perturbations  $\varkappa$  small in comparison with wave vectors of the first harmonic  $k_0$ . We may assume that, on the influence of the first harmonic of a perturbation with the wave vector  $\varkappa \sim k_0$ , the 0-harmonic with a wave vector of 0 will respond as a result of the nonlinear resonant interaction [8, 15] if it is possible in the system and the law of conservation of energy is realized.

Recently in works [16, 17] concerning the same problem as in [10] but on the basis of the system obtained [18, 19] from the Euler equations of motion and at the refusal from additional artificial assumptions about a character of the dependence of the zero harmonic on time, it is discovered that, at  $\varkappa \simeq k_0$ , there is really a band of MI. There arises a question whether this can be obtained in the Hamiltonian approach [10]. Work [10] is written very shortly. We have checked and reproduced all the results of work [10] in more direct way. At the same time, some little inaccuracies have been specified. Their elimination allows us to describe the type of MI indicated in [17] within the Hamiltonian method as well.

# 2. The Hamiltonian, its formal expansion in an integro-power series and equations of motion in the Fourier representation

In the Hamilton formalism for potential nonlinear waves, the equation of motion for the 'complex normal coordinate'  $a(\mathbf{k}, t)$  can be written in the form of the Hamilton equation

$$\frac{\partial a(\mathbf{k},t)}{\partial t} = -i \frac{\delta H}{\delta \overline{a}(\mathbf{k},t)} \tag{1}$$

and a complex conjugate equation. Here, k is a horizontal wave vector  $k = (k_x, k_y)$ , and H is the Hamiltonian of waves as a functional of a(k) and  $\overline{a}(k)$ . For waves on a surface of an ideal fluid, the profile of a wave (an increase and a decrease of the surface)  $\eta(x, t)$  is related to a(k, t) by the formula

$$\eta(\boldsymbol{x},t) = \frac{1}{2\pi} \int \left(\frac{\omega(\boldsymbol{k})}{2g}\right)^{1/2} \left(a(\boldsymbol{k},t) + \overline{a}(-\boldsymbol{k},t)\right) e^{i\boldsymbol{k}\boldsymbol{x}} d\boldsymbol{k}, \qquad \omega(\boldsymbol{k}) = \sqrt{g|\boldsymbol{k}| \tanh(|\boldsymbol{k}|h)},$$

where g is the gravitational acceleration, h is the depth of a fluid and x = (x, y) is a vector of horizontal coordinates.

In the variables a(k),  $\overline{a}(k)$ , the Hamiltonian is expanded in a series in degrees of a(k) and  $\overline{a}(k)$  [10]:

$$H = \int_{-\infty}^{\infty} \omega(k)a(k)\overline{a}(k) dk + \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V(k, k_1, k_2)(\overline{a}(k)a(k_1)a(k_2) + a(k)\overline{a}(k_1)\overline{a}(k_2))\delta(k - k_1 - k_2) dk dk_1 dk_2 + \frac{1}{3} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U(k, k_1, k_2)(a(k)a(k_1)a(k_2) + \overline{a}(k)\overline{a}(k_1)\overline{a}(k_2))\delta(k + k_1 + k_2) dk dk_1 dk_2 + \frac{1}{2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} W(k, k_1, k_2, k_3)\overline{a}(k)\overline{a}(k_1) \times a(k_2)a(k_3)\delta(k + k_1 - k_2 - k_3) dk dk_1 dk_2 dk_3.$$
(2)

Hereafter the wavevectors k are denoted as scalars k for simplicity of notation (including integration variables).

In the cases of infinite depth and finite arbitrary one, the expansion coefficients  $V(k, k_1, k_2)$ ,  $U(k, k_1, k_2)$ ,  $W(k, k_1, k_2, k_3)$  were determined in [3, 4] and [10], respectively. We mention a number of works, for example [20–30] devoted to both these coefficients and the development of the approach. We will present the relevant expressions following the notations in [22] for the further calculations and the establishment of a correspondence with the nonlinear coefficients obtained in [17] by the method of multiple scales:

$$V(k, k_1, k_2) = -V_0(-k, k_1, k_2) - V_0(-k, k_2, k_1) + V_0(k_1, k_2, -k),$$

$$U(k, k_1, k_2) = V_0(k, k_1, k_2) + V_0(k, k_2, k_1) + V_0(k_1, k_2, k),$$

$$V_0(k, k_1, k_2) = -N_0 N_1 M_2 E_{0,1}^{(3)}, \qquad E_{0,1}^{(3)} = -\frac{1}{2 \cdot 2\pi} \left( (\mathbf{k} \cdot \mathbf{k}_1) + q_0 q_1 \right),$$

$$W(k, k_1, k_2, k_3) = W_0(-k, -k_1, k_2, k_3) + W_0(k_2, k_3, -k, -k_1) - W_0(-k, k_2, -k_1, k_3) - W_0(-k_1, k_2, -k, k_3) - W_0(-k, k_3, -k_1, k_2) - W_0(-k_1, k_3, -k, k_2),$$

$$W_0(k, k_1, k_2, k_3) = -2N_0 N_1 M_2 M_3 E_{0,1,2,3}^{(4)},$$
(3)

$$E_{0,1,2,3}^{(4)} = -\frac{1}{8 \cdot (2\pi)^2} (2|\mathbf{k}|^2 q_1 + 2|\mathbf{k}_1|^2 q_0 - q_0 q_1 (q_{0+2} + q_{1+2} + q_{0+3} + q_{1+2})),$$
  

$$N(\mathbf{k}) = \left(\frac{\omega(\mathbf{k})}{2q(\mathbf{k})}\right)^{1/2}, \quad M(\mathbf{k}) = \left(\frac{q(\mathbf{k})}{2\omega(\mathbf{k})}\right)^{1/2}, \qquad q(\mathbf{k}) = |\mathbf{k}| \tanh(|\mathbf{k}|h).$$

Varying Hamiltonian (2), we obtain the equation of motion for a(k, t) as the Hamilton equation unified in the approximation  $\varepsilon^3$  for the standard Hamiltonian (2) as

$$\frac{\partial}{\partial t}a(k,t) + \mathbf{i}[\omega(k)a(k) + \int_{-\infty}^{\infty} V(k,k-\xi,\xi)a(\xi)a(k-\xi)\,\mathrm{d}\xi + 2\int_{-\infty}^{\infty} V(k+\xi,k,\xi)\overline{a}(\xi)a(k+\xi)\,\mathrm{d}\xi + \int_{-\infty}^{\infty} U(-k-\xi,k,\xi)\overline{a}(\xi)\overline{a}(-k-\xi)\,\mathrm{d}\xi + \int_{-\infty}^{\infty}\int_{-\infty}^{\infty} W(\xi+\zeta-k,k,\xi,\zeta)a(\xi)a(\zeta)\overline{a}(\xi+\zeta-k)\,\mathrm{d}\xi\,\mathrm{d}\zeta] = 0.$$

$$(4)$$

Note that the coefficient V is insensitive to the permutation of the second and third arguments, since the second term of Hamiltonian (2) is symmetric with respect to the permutation of integration variables  $k_1$  and  $k_2$ . Similarly, U is insensitive to the permutation of its all arguments, and W is insensitive to the permutation of the first and second arguments and (or) the third and fourth arguments.

# **3.** Equation of motion for the system of Fourier amplitudes of the first and zero harmonics

Let the wave field represent a pulse of oscillating waves with the central wave vector  $k_0$ . Then the Fourier amplitude of the first harmonic and its conjugate quantity are concentrated near the wave vector  $k_0$ ,

$$a_1 = a_1(k, t)\delta(k - k_0).$$
(5)

Nonlinear terms of the equations of motion generate the non-oscillating component of a field (the zero harmonic) and the second and higher harmonics. Their account will be conducted by the expansion in the formal small parameter  $\varepsilon$ :

$$a = \varepsilon a_1 + \varepsilon^2 (b + a_2). \tag{6}$$

The zero harmonic and its conjugate are concentrated near the wave vector k = 0,

$$\rightarrow b(k,t)\delta(k), \qquad b \rightarrow b(k,t)\delta(k),$$
(7)

and the second harmonic

h

a

$$=a_{21}+a_{22}$$
 (8)

consists of both a component of the wave field

$$a_{21} = a_{21}(k,t)\delta(k-2k_0),\tag{9}$$

concentrated near the wave vector  $2k_0$  and that

$$a_{22} = a_{22}(k,t)\delta(k+2k_0),\tag{10}$$

concentrated near  $-2k_0$ .

With the purpose to construct the approximate equations of motion for the Fourier amplitudes of the lowest harmonics  $a_1$  and b, we substitute (6) into (4) and we collect terms with the same degrees of  $\varepsilon$ .

#### *3.1.* The first order in $\varepsilon$

In the first order in  $\varepsilon$ , we obtain the equations of motion for the first harmonic in the linear approximation as

$$\frac{\partial}{\partial t}a_1(k) + \mathrm{i}\omega(k)a_1(k) = 0. \tag{11}$$

#### 3.2. The second order in $\varepsilon$

In the order of  $\varepsilon^2$ , the equations of motion for the zero and second harmonics look as

$$\frac{\partial}{\partial t}a_{2}(k) + i\omega(k)a_{2}(k) + \frac{\partial}{\partial t}b(k) + i\omega(k)b(k) + i\int_{-\infty}^{\infty}a_{1}(\xi)V(k, k-\xi, \xi)a_{1}(k-\xi)\,\mathrm{d}\xi + 2i\int_{-\infty}^{\infty}\overline{a}_{1}(\xi)V(k+\xi, k, \xi)a_{1}(k+\xi)\,\mathrm{d}\xi + i\int_{-\infty}^{\infty}\overline{a}_{1}(\xi)U(k, -k-\xi, \xi)\overline{a}_{1}(-k-\xi)\,\mathrm{d}\xi = 0.$$
(12)

In the first nonlinear term in (12), we consider that it includes the first harmonics  $a_1(\xi)$  and  $a_1(k - \xi)$  concentrated on the wave vector  $k_0$  (5). Therefore,  $\xi = k_0$  and  $k - \xi = k_0$ . Hence, the integration variable  $\xi$  is concentrated in a neighbourhood of  $k_0$  and the wave vector k, for which this nonlinear term is different from zero, is  $2k_0$ . Thus, the first nonlinear term should be grouped together with the linear term  $\frac{\partial}{\partial t}a_{21}(k) + i\omega(k)a_{21}(k)$ , which is also concentrated on the wave vector  $2k_0$ . Thus, we obtain the evolutionary equation for the first component  $a_{21}(k, t)$  of the Fourier amplitude of the second harmonic

$$2k_0: \quad \frac{\partial}{\partial t}a_{21}(k) + i\omega(k)a_{21}(k) + iV(2k_0, k_0, k_0)\int_{-\infty}^{\infty}a_1(\xi)a_1(k-\xi)\,d\xi = 0. \tag{13}$$

Similarly, we obtain the evolutionary equation for  $a_{22}(k, t)$  and b(k, t):

$$-2k_0: \quad \frac{\partial}{\partial t}a_{22}(k) + i\omega(k)a_{22}(k) + iU(-2k_0, k_0, k_0)\int_{-\infty}^{\infty} \overline{a}_1(\xi)\overline{a}_1(-k-\xi)\,\mathrm{d}\xi = 0, \tag{14}$$

$$0: \quad \frac{\partial}{\partial t} \boldsymbol{b}(k) + \mathrm{i}\omega(k)\boldsymbol{b}(k) + 2\mathrm{i}V(k_0, k_0, k) \int_{-\infty}^{\infty} \overline{a}_1(\xi)a_1(k+\xi)\,\mathrm{d}\xi = 0.$$
(15)

Let us remark that in (15),  $V(k_0, k, k_0)$  is changed to  $V(k_0, k_0, k)$  taking into account a symmetry of permutations of the second and third arguments  $V(k, k_1, k_2)$  in (3).

Equations (13) and (14) allow one to express the second harmonic through the first one in order to remove the second harmonic from all formulas in the approximation  $\varepsilon^3$ . For  $a_{21}(k, t)$ , in view of the time dependence  $a_{21}(k, t) \sim e^{-2i\omega(k_0)t}$ , equation (13) yields

$$a_{21}(k) = -\frac{V(2k_0, k_0, k_0)}{\omega(2k_0) - 2\omega(k_0)} \int_{-\infty}^{\infty} a_1(\xi) a_1(k - \xi) \,\mathrm{d}\xi.$$
(16)

Taking the time dependence  $a_{22}(k, t) \sim e^{2i\omega(k_0)t}$  into account, it follows from equation (14) that

$$a_{22}(k) = -\frac{U(-2k_0, k_0, k_0)}{\omega(2k_0) + 2\omega(k_0)} \int_{-\infty}^{\infty} \overline{a}_1(\xi) \overline{a}_1(-k-\xi) \,\mathrm{d}\xi.$$
(17)

We will not integrate equation (15) to avoid the additional assumptions about a character of the dependence b(k) on time. Below, we will use (15) as the equation of motion for the 0-harmonic b(k) and include it in the system with the equation for the first harmonic  $a_1(k)$  which will be deduced in what follows.

#### *3.3.* The third order in $\varepsilon$

Here, we obtain the equation of motion for the first harmonic  $a_1(k)$  in the  $\varepsilon^3$  approximation. Nonlinear terms look as

$$i \int_{-\infty}^{\infty} a_{2}(\xi) V(k, k - \xi, \xi) a_{1}(k - \xi) d\xi + 2i \int_{-\infty}^{\infty} \overline{a}_{1}(\xi) V(k + \xi, k, \xi) a_{2}(k + \xi) d\xi + i \int_{-\infty}^{\infty} a_{1}(\xi) V(k, k - \xi, \xi) a_{2}(k - \xi) d\xi + i \int_{-\infty}^{\infty} \overline{a}_{1}(\xi) U(k, -k - \xi, \xi) \overline{a}_{2}(-k - \xi) d\xi + 2i \int_{-\infty}^{\infty} \overline{a}_{2}(\xi) V(k + \xi, k, \xi) a_{1}(k + \xi) d\xi + i \int_{-\infty}^{\infty} \overline{a}_{2}(\xi) U(k, -k - \xi, \xi) \overline{a}_{1}(-k - \xi) d\xi$$

$$+i\int_{-\infty}^{\infty} a_{1}(\xi)V(k, k-\xi, \xi)b(k-\xi) d\xi +i\int_{-\infty}^{\infty} b(\xi)V(k, k-\xi, \xi)a_{1}(k-\xi) d\xi +2i\int_{-\infty}^{\infty} \overline{a}_{1}(\xi)V(k+\xi, k, \xi)b(k+\xi) d\xi +2i\int_{-\infty}^{\infty} \overline{b}(\xi)V(k+\xi, k, \xi)a_{1}(k+\xi) d\xi +i\int_{-\infty}^{\infty} \overline{a}_{1}(\xi)U(k, -k-\xi, \xi)\overline{b}(-k-\xi) d\xi +i\int_{-\infty}^{\infty} \overline{b}(\xi)U(k, -k-\xi, \xi)\overline{a}_{1}(-k-\xi) d\xi +i\int_{-\infty}^{\infty} a_{1}(\zeta)\int_{-\infty}^{\infty} a_{1}(\xi)W(k, -k+\xi+\zeta, \xi, \zeta)\overline{a}_{1}(-k+\xi+\zeta) d\xi d\zeta$$
(18)

We divide them into 5 groups.

(1) In the first three terms (18) which contain the second harmonic  $a_2$  we consider that it consists of the component of a wave field  $a_{21}$  (9) concentrated in a neighbourhood of the wave vector  $2k_0$  and the component of a wave field  $a_{22}$  (10), concentrated in the region of  $-2k_0$ , the amplitude of the first harmonic and its conjugate being concentrated on the wave vector  $k_0$  (5). Arguing as in the derivation of (13), we can conclude that the kernels can be taken out of the integrals:

$$iV(3k_{0}, 2k_{0}, k_{0}) \int_{-\infty}^{\infty} a_{1}(\xi)a_{21}(k-\xi) d\xi + 2iV(2k_{0}, k_{0}, k_{0}) \int_{-\infty}^{\infty} \overline{a}_{1}(\xi)a_{21}(k+\xi) d\xi + iV(3k_{0}, k_{0}, 2k_{0}) \int_{-\infty}^{\infty} a_{1}(\xi)a_{21}(k-\xi) d\xi + iV(-k_{0}, -2k_{0}, k_{0}) \int_{-\infty}^{\infty} a_{1}(\xi)a_{22}(k-\xi) d\xi + 2iV(-2k_{0}, -3k_{0}, k_{0}) \int_{-\infty}^{\infty} \overline{a}_{1}(\xi)a_{22}(k+\xi) d\xi + iV(-k_{0}, k_{0}, -2k_{0}) \int_{-\infty}^{\infty} a_{1}(\xi)a_{22}(k-\xi) d\xi.$$
(19)

Moreover, these terms are concentrated at k equal to  $3k_0$ ,  $k_0$ ,  $3k_0$ ,  $-k_0$ ,  $-3k_0$  and  $-k_0$ , respectively. Further, we retain only the second term (19) as essential, because it is concentrated on the wave vector  $k_0$  of the first harmonic, for which we will construct an evolutionary equation of motion.

(2) Analogously, in the following three terms (18) which contain the conjugate of the second harmonic  $\overline{a}_2$ , we take into account that it consists of the component of a wave field  $\overline{a}_{21}$  concentrated in the region of the wave vector  $2k_0$  ( $\overline{a}_{21} = \overline{a}_{21}(k, t)\delta(k - 2k_0)$ ) and the component  $\overline{a}_{22}$  concentrated in a vicinity of  $-2k_0$  ( $\overline{a}_{22} = \overline{a}_{22}(k, t)\delta(k + 2k_0)$ ). This allows us again to take out the kernels of the integrals:

$$iU(-3k_0, 2k_0, k_0) \int_{-\infty}^{\infty} \overline{a}_1(\xi) \overline{a}_{21}(-k-\xi) d\xi + 2iV(k_0, -k_0, 2k_0) \int_{-\infty}^{\infty} \overline{a}_{21}(-k-\xi) a_1(-\xi) d\xi + iU(-3k_0, k_0, 2k_0) \int_{-\infty}^{\infty} \overline{a}_1(\xi) \overline{a}_{21}(-k-\xi) d\xi$$

$$+ iU(k_{0}, -2k_{0}, k_{0}) \int_{-\infty}^{\infty} \overline{a}_{1}(\xi) \overline{a}_{22}(-k-\xi) d\xi + 2iV(k_{0}, 3k_{0}, -2k_{0}) \int_{-\infty}^{\infty} \overline{a}_{22}(-k-\xi) a_{1}(-\xi) d\xi + iU(k_{0}, k_{0}, -2k_{0}) \int_{-\infty}^{\infty} \overline{a}_{1}(\xi) \overline{a}_{22}(-k-\xi) d\xi,$$
(20)

These terms are concentrated at k equal to  $-3k_0$ ,  $-k_0$ ,  $-3k_0$ ,  $k_0$ ,  $3k_0$  and  $k_0$ , respectively. In (20), the fourth and sixth terms are essential as they are concentrated on the wave vector  $k_0$  of the first harmonic.

(3) In the following three terms (18) containing the zero harmonic b, we consider that it is concentrated in a neighbourhood of the wave vector k = 0 (7), the amplitude of the first harmonic and its conjugate being concentrated on the wave vector  $k_0$  (5). This allows us to partially fix the arguments of kernels:

$$i \int_{-\infty}^{\infty} a_{1}(\xi) V(k_{0}, k_{0} - \xi, k_{0}) b(k - \xi) d\xi + i \int_{-\infty}^{\infty} a_{1}(\xi) V(k_{0}, k_{0}, k_{0} - \xi) b(k - \xi) d\xi + 2i \int_{-\infty}^{\infty} \overline{a}_{1}(\xi) V(k_{0} + \xi, k_{0}, -k_{0}) b(k + \xi) d\xi.$$
(21)

Here, the first and second terms are concentrated at  $k = k_0$ , whereas the third one is concentrated at  $k = -k_0$ . So we keep only the first and second terms.

(4) Analogously, in the following three terms (18) which contain the conjugate of the zero harmonic  $\overline{b}$ , we consider that it is concentrated on the wave vector k = 0 (5). This allows us to partially fix the arguments of kernels:

$$2i \int_{-\infty}^{\infty} \overline{b}(\xi - k) V(k_0, k_0, \xi - k_0) a_1(\xi) d\xi + i \int_{-\infty}^{\infty} \overline{b}(-k - \xi) U(k_0, -k_0 - \xi, k_0) \overline{a}_1(\xi) d\xi + i \int_{-\infty}^{\infty} \overline{b}(-k - \xi) U(k_0, k_0, -k_0 - \xi) \overline{a}_1(\xi) d\xi.$$
(22)

Now the first term is concentrated at  $k = k_0$ , and the second and third ones are concentrated at  $k = -k_0$ . Further, only the first term is kept as the main one.

(5) As for the last term (18), we consider that the amplitude of the first harmonic and its conjugate are concentrated on the wave vector  $k_0$  (5). This allows us again to take out the kernels of the integrals:

$$iW(k_0, k_0, k_0, k_0) \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} a_1(\xi) a_1(\zeta) \overline{a}_1(-k + \xi + \zeta) \, \mathrm{d}\xi \, \mathrm{d}\zeta.$$
(23)

We now construct the equation of motion for the first harmonic from the linear terms in the  $\varepsilon$  approximation (11) and from the above-mentioned basic nonlinear terms in the  $\varepsilon^3$  approximation from (19)-(22):

$$2iV(2k_0, k_0, k_0) \int_{-\infty}^{\infty} \overline{a}_1(\xi) a_{21}(k+\xi) \,\mathrm{d}\xi + 2iU(-2k_0, k_0, k_0) \int_{-\infty}^{\infty} \overline{a}_1(\xi) \overline{a}_{22}(-k-\xi) \,\mathrm{d}\xi \quad (24)$$

$$2i\int_{-\infty}^{\infty} V(k_0, k_0, k_0 - \xi)b(k - \xi)a_1(\xi) d\xi + 2i\int_{-\infty}^{\infty} V(k_0, k_0, \xi - k_0)\overline{b}(\xi - k)a_1(\xi)d\xi$$
(25)

and term (23). In these equations, we took the symmetry of the coefficients  $V(k_1, k_2, k_3)$ ,  $U(k_1, k_2, k_3)$  relative to permutations of the arguments into account [10, 22]. Then we

introduce the expressions for the components of the second harmonic  $a_{21}$  and  $a_{22}$  [(16), (17)] given in terms of the first harmonic obtained in the  $\varepsilon^2$  approximation into (24). In such a way, we obtain the equations of motion for the first harmonic:

$$\begin{aligned} \frac{\partial}{\partial t}a_1(k) + \mathrm{i}\omega(k)a_1(k) &- 2\mathrm{i}\left(\frac{V^2(2k_0, k_0, k_0)}{\omega(2k_0) - 2\omega(k_0)} + \frac{U^2(-2k_0, k_0, k_0)}{\omega(2k_0) + 2\omega(k_0)}\right) \\ &\times \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \overline{a}_1(\xi)a_1(\zeta)a_1(\xi - \zeta + k)\,\mathrm{d}\zeta\,\mathrm{d}\xi \\ &+ 2\mathrm{i}\int_{-\infty}^{\infty} a_1(\xi)[V(k_0, k_0, k_0 - \xi)b(k - \xi) + V(k_0, k_0, \xi - k_0)\overline{b}(\xi - k)]\,\mathrm{d}\xi \\ &+ \mathrm{i}W(k_0, k_0, k_0, k_0)\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} a_1(\zeta)a_1(\xi)\overline{a}_1(\xi + \zeta - k)\,\mathrm{d}\xi\,\mathrm{d}\zeta = 0 \end{aligned}$$

or

$$\frac{\partial}{\partial t}a(k) + i\omega(k)a(k) + i\int_{-\infty}^{\infty}a(\xi)[f(k_0 - \xi)b(k - \xi) + f(\xi - k_0)\overline{b}(\xi - k)]\,\mathrm{d}\xi + i\lambda\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}a(\zeta)a(\xi)\overline{a}(\zeta + \xi - k)\,\mathrm{d}\xi\,\mathrm{d}\zeta = 0,$$
(26)

where we denote

$$f(k) = 2V(k_0, k_0, k),$$
(27)

$$\lambda = W(k_0, k_0, k_0, k_0) - 2\left(\frac{V^2(2k_0, k_0, k_0)}{\omega(2k_0) - 2\omega(k_0)} + \frac{U^2(-2k_0, k_0, k_0)}{\omega(2k_0) + 2\omega(k_0)}\right)$$
(28)

and  $a_1$  is designated as a. In the same notations, we rewrite the equations for the 0-harmonic (15) as

$$\frac{\partial}{\partial t}b(k) + \mathrm{i}\omega(k)b(k) + \mathrm{i}f(k)\int_{-\infty}^{\infty}\overline{a}(\xi)a(k+\xi)\,\mathrm{d}\xi = 0.$$
(29)

Equations (26) and (29) coincide with equations (19) and (20) in [10], though they are obtained by the somewhat different method, as compared with that in [10], of step-by-step account of approximations. But there is one difference. Expression (27) for f(k) differs by the sequence of arguments from formula (18),  $f(k) = 2V(k, k_0, k_0)$ , in [10]. This difference cannot be removed by using properties of the symmetry of coefficients [22]. This can be seen from formula (3) for the coefficient  $V(k, k_1, k_2)$ .

#### 4. Modulation instability

We present the solution of the system of equations of motion (26) and (29) which contains the correction on the nonlinearity as

$$a(k) = \mathcal{A}_0 e^{-it(\omega(k_0) + \lambda_1 \mathcal{A}_0^2)} \delta(k - k_0), \qquad b(k) = \lambda_2 \mathcal{A}_0^2 \delta(k).$$

Substituting it in (26) and (29), we obtain

$$\lambda_1^{(1)} = \lambda, \qquad \lambda_2^{(1)} = 0, \qquad \lambda_1^{(2)} = \lambda - 2\frac{f^2(0)}{\omega(0)}, \qquad \lambda_2^{(2)} = -\frac{f(0)}{\omega(0)}.$$
(30)

For waves on the surface of a fluid at small  $\varkappa$ ,  $\omega(\varkappa) \sim \varkappa$  and, as seen from (38),  $f(\varkappa) \sim \sqrt{\varkappa}$ . The expression for  $\lambda_2^{(2)}$  diverges, therefore we choose the first variant. We introduce a perturbation

$$a(k) = e^{-it(\omega(k_0) + \lambda_1 A_0^2)} (\mathcal{A}_0 \delta(k - k_0) + \varepsilon \alpha(k) e^{-i\Omega t} \delta(k - k_0 - \varkappa) + \varepsilon \alpha(k) e^{i\Omega t} \delta(k - k_0 + \varkappa)), \quad (31)$$
  
$$b(k) = \lambda_2 \mathcal{A}_0^2 \delta(k) + \varepsilon \beta(k) e^{-i\Omega t} \delta(k - \varkappa) + \varepsilon \beta(k) e^{i\Omega t} \delta(k + \varkappa), \quad (32)$$

where  $\alpha(k)$  and  $\beta(k)$  are real quantities.

Let us explore a possibility of existence of the imaginary part of the frequency  $\Omega$  for some wave vectors of a perturbation wave  $\varkappa$  depending on the normalized depth of a fluid  $k_0h$ , which will testify the instability of a nonperturbed wave at such wave vectors of the perturbation. After the substitution of (31) and (32) into the linearized equations of motion (26) and (29), we obtain a system of homogeneous equations for  $\alpha(k_0 + \varkappa)$  and  $\alpha(k_0 - \varkappa)$ ,  $\beta(\varkappa)$  and  $\beta(-\varkappa)$ :

$$\begin{split} \left(\Omega + \omega(k_0 - \varkappa) - \omega(k_0) + \lambda \mathcal{A}_0^2\right) \alpha(k_0 - \varkappa) \\ &+ \lambda \mathcal{A}_0^2 \alpha(k_0 + \varkappa) + \mathcal{A}_0 \left[f(-\varkappa)\beta(-\varkappa) + f(\varkappa)\beta(\varkappa)\right] = 0, \\ \left(\Omega - \omega(k_0 + \varkappa) + \omega(k_0) - \lambda \mathcal{A}_0^2\right) \alpha(k_0 + \varkappa) \\ &- \lambda \mathcal{A}_0^2 \alpha(k_0 - \varkappa) - \mathcal{A}_0 \left[f(-\varkappa)\beta(-\varkappa) + f(\varkappa)\beta(\varkappa)\right] = 0, \\ \left(\Omega + \omega(\varkappa)\right) \beta(-\varkappa) + \mathcal{A}_0 f(-\varkappa) \left[\alpha(k_0 - \varkappa) + \alpha(k_0 + \varkappa)\right] = 0, \\ \left(\Omega - \omega(\varkappa)\right) \beta(\varkappa) - \mathcal{A}_0 f(\varkappa) \left[\alpha(k_0 - \varkappa) + \alpha(k_0 + \varkappa)\right] = 0. \end{split}$$
Excepting  $\beta(\varkappa)$  and  $\beta(-\varkappa)$ , we obtain   
 $\left(\Omega + \omega(k_0 - \varkappa) - \omega(k_0) - \lambda(\Omega)\mathcal{A}_0^2\right) \alpha(k_0 - \varkappa) - \lambda(\Omega)\mathcal{A}_0^2 \alpha(k_0 + \varkappa) = 0. \end{split}$ 

$$(\Omega - \omega(k_0 + \varkappa) - \omega(k_0) - \lambda(\Omega)\mathcal{A}_0^2) \alpha(k_0 - \varkappa) - \lambda(\Omega)\mathcal{A}_0^2 \alpha(k_0 + \varkappa) = 0,$$

$$(\Omega - \omega(k_0 + \varkappa) + \omega(k_0) + \lambda(\Omega)\mathcal{A}_0^2) \alpha(k_0 + \varkappa) + \lambda(\Omega)\mathcal{A}_0^2 \alpha(k_0 - \varkappa) = 0,$$

where

$$\lambda(\Omega) = -\lambda + \lambda^{(0)}(\Omega), \tag{33}$$

$$\lambda^{(0)}(\Omega) = \frac{f^2(-\varkappa)}{\omega(\varkappa) + \Omega} + \frac{f^2(\varkappa)}{\omega(\varkappa) - \Omega}.$$
(34)

The superscript in  $\lambda^{(0)}(\Omega)$  underlines that it is the contribution to the nonlinear interaction from the 0-harmonic. Equating the determinant to zero gives the required equation for the perturbation frequency  $\Omega$ 

$$(\Omega - \delta)^2 = \Delta^2 - 2\lambda(\Omega)\mathcal{A}_0^2\Delta, \tag{35}$$

where

$$\Delta = \frac{1}{2}(\omega(k_0 + \varkappa) + \omega(k_0 - \varkappa)) - \omega(k_0), \qquad \delta = \frac{1}{2}(\omega(k_0 + \varkappa) - \omega(k_0 - \varkappa)).$$
  
In the extended form, relation (35) looks like

$$(\Omega + \omega(k_0 - \varkappa) - \omega(k_0))(\Omega - \omega(k_0 + \varkappa) + \omega(k_0)) = -2\lambda(\Omega)\mathcal{A}_0^2\Delta$$
(36)

and coincides with that in [10].

The first term in (33) is calculated from (28). For waves on the surface of a fluid of finite depth, we obtain

$$\lambda = \frac{k_0^3}{32\pi^2} \frac{9\sigma^4 - 10\sigma^2 + 9}{\sigma^3}, \qquad \sigma = \tanh k_0 h.$$
(37)

Let us calculate the second term in (33). To derive  $f(x) = 2V(k_0, k_0, x)$  according to (27), we simplify the coefficient  $V(k, k_1, k_2)$  (3). We have

$$f(\varkappa) = \frac{k_0^{3/2} \omega_0^{1/2}}{4\sqrt{2}\pi \sqrt{\sigma}} \left( 2\frac{\varkappa}{k_0} \sqrt{\frac{\omega_0}{\omega(\varkappa)}} + (1 - \sigma^2) \sqrt{\frac{\omega(\varkappa)}{\omega_0}} \right).$$
(38)

Since our purpose is to investigate all four roots of equation (35), we do not approximate  $\Omega$  in the denominator in (34), as it was made in [10]. According to (34), we obtain

$$\lambda^{(0)}(\Omega) = \frac{k_0^3}{16\pi^2\sigma} \left( \frac{\varkappa^2}{\omega^2(\varkappa) - \Omega^2} \left( 2\frac{\omega_0}{k_0} + (1 - \sigma^2)\frac{\Omega}{\varkappa} \right)^2 + (1 - \sigma^2)^2 \right).$$
(39)

### 4.1. $\varkappa \ll k_0$ . Comparison with the known results

In this case, we can approximate  $\Omega$  in the denominator in (34). The asymptotes of four roots  $\Omega(\varkappa)$  of equation (36) at small  $\varkappa$  and  $\mathcal{A}_0$  read

$$\Omega_{1,2} = c_g \varkappa \mp \frac{1}{6} \frac{\partial^3 \omega(k_0)}{\partial k^3} \varkappa^3, \qquad \Omega_{3,4} = \pm \sqrt{gh} \varkappa, \qquad c_g = \frac{\omega_0}{2k_0} \left( 1 + \frac{1 - \sigma^2}{\sigma} k_0 h \right),$$
(40)

where  $c_g$  is the group velocity of linear waves. They are shown (after the normalization  $\widehat{\Omega} = \frac{\Omega}{\omega_0}, \widehat{\varkappa} = \frac{\varkappa}{k_0}$ ) by dotted curves 1a, 2a, 3a, 4a on the plots of the real part Re  $\widehat{\Omega}$  in figure 1. Setting the purpose to determine the imaginary part of the first two roots in the next approximation in the case of  $\varkappa \ll k_0$ , we can use the asymptote  $\Omega = \varkappa c_g$  in (39) (see also [25, 30]). We get

$$\lambda(\Omega)|_{\Omega=c_{g^{\chi}}} = \frac{k_{0}^{3}}{16\pi^{2}\sigma} \left( -\frac{9\sigma^{4} - 10\sigma^{2} + 9}{2\sigma^{2}} + \frac{1}{gh - c_{g}^{2}} \left( 2\frac{\omega_{0}}{k_{0}} + (1 - \sigma^{2})c_{g} \right)^{2} + (1 - \sigma^{2})^{2} \right).$$
(41)

Since  $\Delta < 0$  for a convex function  $\omega(k)$  according to the Jensen inequality, equation (35) can have complex roots, if  $\lambda(\Omega) < 0$ . Coefficient (41) (obtained at  $f(\varkappa) = 2V(k_0, k_0, \varkappa)$ ) changes a sign at  $k_0h = 1.363$  that coincides with the depth at which the Benjamin–Feir MI disappears. Some mismatch of (41) with formula (29) in [10] is related to the above-mentioned difference in the sequence of arguments in (27).

We now compare (36) with the corresponding equation

$$(\Omega + \omega(k_0 - \varkappa) - \omega(k_0))(\Omega - \omega(k_0 + \varkappa) + \omega(k_0)) = -2q(\Omega)A_0^2\Delta,$$
(42)

obtained in [17] by the method of multiple scales from the Euler equations of motion. Here,

$$q(\Omega) = \widetilde{q} + q^{(0)}(\Omega) \tag{43}$$

$$\widetilde{q} = \frac{\omega_0 k_0^2}{16\sigma^2} \left( -\frac{9\sigma^4 - 10\sigma^2 + 9}{\sigma^2} + 2\left(\sigma^2 - 1\right)^2 \right),\tag{44}$$

$$q^{(0)}(\Omega) = \frac{\omega_0 k_0^2}{8\sigma^2} \frac{\varkappa^2}{\omega^2(\varkappa) - \Omega^2} \left( 2\frac{\omega_0}{k_0} + (1 - \sigma^2)\frac{\Omega}{\varkappa} \right) \left( 2\frac{\omega_0}{k_0} + (1 - \sigma^2)c_g \right).$$
(45)

and  $q^{(0)}(\Omega)$  is the contribution of the 0-harmonic to the nonlinear interaction. In the special case considered above,  $\varkappa \ll k_0$ , concerning two roots which correspond to the asymptote  $\Omega = \varkappa c_g$ , from (45) we have

$$q^{(0)}(\Omega)|_{\Omega=c_g\varkappa} = \frac{\omega_0 k_0^2}{8\sigma^2} \frac{1}{gh - c_g^2} \left(2\frac{\omega_0}{k_0} + (1 - \sigma^2)c_g\right)^2.$$
 (46)

Taking into account the formula  $A_0^2 = \frac{\sigma}{2\pi^2} \frac{k_0}{\omega_0} \mathcal{A}_0^2$  for the physical amplitude  $A_0$  and the wave amplitude in the Fourier space  $\mathcal{A}_0$ , as well as relations (36) and (42), we should compare



**Figure 1.** Real part of the normed frequency  $\widehat{\Omega}$  versus the normed wave vector  $\widehat{\varkappa}$  for four roots of equation (35) for various depths (respectively, from the top down):  $k_0h = 10$ ; 2, 1.363 and 1.  $k_0A_0 = 0.2$ . The numbering of roots corresponds to that of their asymptotes at small  $\varkappa$  (40). The asymptotes are drawn by dotted lines with a letter *a* near the number of a curve.

the coefficient  $\lambda(\Omega)$  of the given paper with the coefficient  $q(\Omega)$  in [17] multiplied by

$$\frac{\sigma}{2\pi^2} \frac{k_0}{\omega_0}.\tag{47}$$



**Figure 2.** The same as in figure 1 for the imaginary part of  $\widehat{\Omega}$ .

It is seen that expression (43) for  $q(\Omega)$  as the sum of (44) and (46) with regard for (47) is identically equal to expression (41) for  $\lambda(\Omega)$ , which indicates the coincidence of results of the given work and [17] in the case of  $\varkappa \ll k_0$ .

## 4.2. $\varkappa \simeq k_0$ . New instability

At arbitrary  $\varkappa$ , the numerical calculation of solutions of equation (35) is necessary. The equation of the fourth order obtained in [10] was not solved numerically and was reduced to a

0.05			0.05			0.05		0.05		
0.05	$\operatorname{Im}\hat{\Omega}$	()	0.05	nÂ		0.05	Im Ω̂	0.05	$\mathrm{Im}\hat\Omega$	
0.04			0.04			0.04		0.04		
0.03			0.03			0.03		0.03		
0.02 -		۸	0.02		٨	0.02		0.02		
0.01		ŕ	0.01	$\wedge$	ĥ.	0.01	ĥ	0.01		ŕ
0	0.5	1 1.5	U	0.5	1 1.5	0	0.5 1 1.5	0	0.5 1	1.5

**Figure 3.** Imaginary part of the normed frequency  $\widehat{\Omega}$  versus the normed wave vector  $\widehat{\chi}$  for four roots of equation (35) for various  $\chi/k_0$  (respectively, from the left right):  $\chi/k_0 = 0.11$ ; 0.1295; 0.43 and 0.44,  $k_0h = 2$ ,  $k_0A_0 = 0.2$ .

quadratic equation for a small deviation  $\Omega$  from the resonance surface,  $\omega(k_0 + \varkappa) - \omega(k_0) = \omega(k_0) - \omega(k_0 - \varkappa)$ , for the analysis of the instability increment. The results of numerical tabulation of the dependence of the real and imaginary parts of  $\widehat{\Omega} = \frac{\Omega}{\omega_0}$  on  $\widehat{\chi} = \frac{\varkappa}{k_0}$  for four solutions of equation (35) for several values of  $k_0h$  for  $k_0A_0 = 0.2$  are shown in figures 1 and 2. Indexing the roots corresponds to their asymptotes at small  $\varkappa$  (40). In figure 2, except for the known band of instability at  $\varkappa \ll k_0$  (the Benjamin–Feir instability), we observe one more section of instability at  $\varkappa \simeq k_0$ . The third band is the right edge of the known 'eight' of Phillips [8]. Unlike the BF instability which disappears at  $k_0h = 1.363$ , the additional band of instability exists at this and smaller depths.

Let us make a comparison with the calculations by McLean (1982) for two-dimensional wave vectors of perturbations. Restore the two-component notation for wave vectors k in formula (35) (and also in formulae (34), (38), (39), (3) used therein). Introduce the same designations as in the paper by McLean (1982):  $k_0 = (k_0, 0)$  for the carrier wave vector,  $\varkappa = (\kappa, \chi)$  for the perturbation vector, and  $p = \frac{\kappa}{k_0}$ ,  $q = \frac{\chi}{k_0}$  for the normalized perturbation vectors. Figure 3 shows a comparison with figure 2(a) McLean (1982) for  $k_0h = 2$ ,  $k_0A_0 = 0.2$  and q = 0.11, 0.1295, 0.43 and 0.44. The results agree for the most part. The additional band (new instability) appears because we supposed that the zero harmonic evolves with the velocity of slow waves which does not coincide with the group velocity of the first harmonic. Full research on a case 3D and type II instability is supposed to be in a separate work. His paper devotes to confirmation of the existence of the new instability at  $\varkappa \simeq k_0$ .

The essential role in the formation of new instability is played also by the first harmonic  $a_1$  and the 0-harmonic b. Therefore the long-term evolution of the considered instability can lead to the formation of structures intermediate between solitons of the envelope of fast oscillations described by a nonlinear Schrödinger equation and solitary waves without a filling characteristic of shallow water. This type of MI was specified in [17] on the basis of a system of evolutionary equations for the zero and basic harmonics which was obtained by the method of multiple scales from the Euler equations of motion. The reproduction of this result by the Hamiltonian method indicates the validity of both approaches.

#### Acknowledgment

I wish to thank Dr Ivan Gandzha for fruitful discussions.

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